

Schwarz-Christoffel Transformation On A Half Plane

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ABSTRACT :The Schwarz-Christoffel transformation has been studied by many reseachers due to a huge of its application in solving Laplace's equations and studying fluid flow phenomenas (see [3],[4]). The proof of this theorem can find in (see for example [5]). Their method depend on the tangent of $T_j = 1 + i0$ and the rotation of T_j from 0 to π on points $(x, 0)$. In this paper we would like to prove the Shwarz-Christoffeltransformation directly by using the arguments identity of complex number, rotation of it from 0 to 2π and conformal mapping.

Keywords : Complex function, half plane, polygon, analytic function, transformation, Conformal mapping.

I. INTRODUCTION

The Schwarz-Christoffel transformation known as a map from the upper half-plane to simply connected polygon with or without corners at infinity in the complex planes.The Schwarz-Christoffel transformation has been studied by many reseachers due to a huge of its application for example used in physical applications involving fluid movement, heat conduction and electrostatic potential, as well asthe studying of Laplace's equations (see [3],[4]) and also from mathematical point of views (see [1],[2],[6]).

In this paper we study about the proof of the Schwarz-Christoffel theorem. The prove of this theorem can found in (see for example [5]). Their method depend on the tangent of $T_j = 1 + i0$ and the rotation of T_j from 0 to π on points $(x, 0)$. In this paper we would like to prove the Shwarz-Christoffel transformation directly by using the arguments identity of complex number, rotation of it from 0 to 2π and conformal mapping.

II. PRELIMINARIES

We need to review some important definitions and theorems which will be used later from complex analysis to understand the Schwarz-Christoffeltheorem.These definitions and theorems below can be found in the references (see [3], [4]).

Definition 2.1 A complex number is a number of the form $z = a + ib$ where the imaginary unit is defined as $i = \sqrt{-1}$ and a is the real part of z , $a = Re(z)$, and b is the imaginary part of z , $b = Im(z)$. The set of all complex number is written by C .

Definition 2.2. Arguments of complex number

Let r and θ be polar coordinates of the point (a, b) that corresponds to a *nonzero* complex number $z = a + ib$. Since $a = r \cos \theta$ and $b = r \sin \theta$, the number z can be written in *polar form* as $z = r (\cos \theta + i \sin \theta) = |z| e^{i\theta}$, where $|z|$ is a positive real number called the modulus of z , and θ is real number called the argument of z , and written by $\arg z$. The real number θ represents the angle and measured in radians.

Theorem 2.1. Law of arguments of products .

Let $b, c \in C$. Then

$$\arg bc = \arg b + \arg c. \quad (1.1)$$

Theorem 2.2. Law of arguments of power

Let $b, c \in C$. Then

$$\arg b^c = c \arg b. \quad (1.2)$$

Definition 2.3. Complex Function. A complex function f whose domain and range are subsets of the set C of complex numbers.

Definition 2.4. Conformal mapping. Let $w = f(z)$ be a complex mapping defined in a domain D and let z_0 be a point in D . Then we say that $w = f(z)$ is conformal at z_0 if for every pair of smooth oriented curves C_1 and C_2 in D intersecting at z_0 the angle between C_1 and C_2 at z_0 is equal to the angle between the image curves C'_1 and C'_2 at $f(z_0)$ in both magnitude and sense.

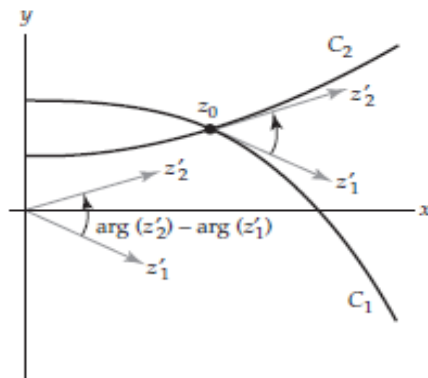


Figure 1.1 The angle between C_1 and C_2 (see [4])

In other words a mapping $w = f(z)$ preserves both angle and shape but it cannot in general the size. Moreover a mapping that is conformal at every point in a domain D is called conformal in D , the conformal mapping relies on the properties of analytic function. The angle between any two intersecting arcs in the z -plane is equal to the angle between the images of the arcs in the w -plane under a linear mapping.

Definition 2.5. Analytic Function. A function $f(z)$ is said to be analytic in a region R of the complex plane if $f(z)$ has a derivative at each point of R . In addition, analytic function is conformal at z_0 if and only if $f'(z) \neq 0$.

Definition 2.6. Polygon. A polygon is a plane figure that is bounded by closed path, composed of a finite sequence of straight-line segments (i.e. a closed polygonal *chain* or *circuit*). These segments are called its *edges* or *sides*, and the points where two edges meet are the polygon's *vertices* (singular: *vertex*) or *corners*.

III. MAIN THEOREM

Theorem (Schwarz-christoffel)

Let P be a polygon in the w -plane with vertices w_1, w_2, \dots, w_n and exterior angles α_k , where $-\pi < \alpha_k < \pi$. There exists a one-to-one conformal mapping $w = f(z)$ from the upper half plane, $Im(z) > 0$ onto G that satisfies the boundary conditions in equations $w_k = f(x_k)$ for $k = 1, 2, \dots, n-1$ and $w_n = f(\infty)$, where $x_1 < x_2 < x_3 < \dots < x_{n-1} < \infty$. Derivative $f'(z)$ is

$$f'(z) = A(z - x_1)^{-\frac{\alpha_1}{\pi}} (z - x_2)^{-\frac{\alpha_2}{\pi}} \dots (z - x_{n-1})^{-\frac{\alpha_{n-1}}{\pi}} \tag{1.3}$$

and the function f can be expressed as an indefinite integral

$$f(z) = B + A \int f'(z) = A(z - x_1)^{-\frac{\alpha_1}{\pi}} (z - x_2)^{-\frac{\alpha_2}{\pi}} \dots (z - x_{n-1})^{-\frac{\alpha_{n-1}}{\pi}} dz \tag{1.4}$$

where A and B are suitably chosen constants. Two of the points $\{x_k\}$ may be chosen arbitrarily, and the constants A and B determine the size and position of P .

IV. PROVE OF THE THEOREM

A transformation $w = f(z)$ constructed by mapping each point on the x axis in z -plane z on w -plane, with $x_1, x_2, \dots, x_{n-1}, x_n$ are the points on the x -axis and $x_1 < x_2 < x_3 < \dots < x_{n-1} < x_n$ where the points on the plane z is the domain of the transformation. These points are mapped in to points on the n -side, is $w_j = f(x_j), j = 1, 2, \dots, n-1$ and $w_n = f(\infty)$ in

w -plane. The function f chosen so that $\arg f'(z)$ different constant value

$$f'(z) = A(z - x_1)^{-k_1} (z - x_2)^{-k_2} \dots (z - x_{n-1})^{-k_{n-1}} \tag{1.5}$$

where A is a complex constant and each k_j , with $j = 1, 2, 3, n-1$ are real constants.

From equation (1.5) we taking the absolute value, then we have

$$\begin{aligned} |f'(z)| &= |A(z - x_1)^{-k_1} (z - x_2)^{-k_2} \dots (z - x_{n-1})^{-k_{n-1}}| \\ &= |A(z - x_1)^{-k_1}| |(z - x_2)^{-k_2}| \dots |(z - x_{n-1})^{-k_{n-1}}| \\ &= \left| \frac{A}{(z - x_1)^{k_1}} \right| \left| \frac{1}{(z - x_2)^{k_2}} \right| \dots \left| \frac{1}{(z - x_{n-1})^{k_{n-1}}} \right|, \end{aligned}$$

by using $(z - x_j)^{-k_j} = |z - x_j|^{-k_j} \exp(-ik_j \theta_j)$, $(-\frac{\pi}{2} < \theta_j < \frac{3\pi}{2})$ where $\theta_j = \arg(z - x_j)$ and $j = 1, 2, \dots, n - 1$, then $f'(z)$ is analytic everywhere in the half plane, so

$$|f'(z)| = \left| \frac{A e^{-ik_1 \theta_1}}{(z-x_1)^{k_1}} \right| \left| \frac{e^{-ik_2 \theta_2}}{(z-x_2)^{k_2}} \right| \cdots \left| \frac{e^{-ik_{n-1} \theta_{n-1}}}{(z-x_{n-1})^{k_{n-1}}} \right|$$

$$= \frac{|A| |e^{-ik_1 \theta_1}| |e^{-ik_2 \theta_2}| \cdots |e^{-ik_{n-1} \theta_{n-1}}|}{|z-x_1|^{k_1} |z-x_2|^{k_2} \cdots |z-x_{n-1}|^{k_{n-1}}}$$

$$< \frac{A}{|z-x_1|^{k_1} |z-x_2|^{k_2} \cdots |z-x_{n-1}|^{k_{n-1}}}$$
(1.6)

By using $|e^{-ik_{1j} \theta_j}| = 1$ and

$$\frac{2}{|z|} < |z - x_j| < 2|z| \text{ and}$$

$$\frac{1}{2|z|} < \frac{1}{|z - x_j|} < \frac{2}{|z|}$$

to equation (1.6) we have that

equation (1.6) $< \frac{2A}{|z|^{k_1}} < \frac{1}{|z|^{k_2}} \cdots \frac{1}{|z|^{k_{n-1}}}$

$$= \frac{2A}{|z|^{k_1 k_2 + \dots + k_{n-1}}}$$

Since $k_1 + k_2 + \dots + k_{n-1} + x_n = 2, -1 < k_j < 1, (j = 1, 2, \dots, n)$ then

$$\frac{2A}{|z|^{k_1 k_2 + \dots + k_{n-1}}} = \frac{2A}{|z|^{2-k_n}}$$

It means, that there exist $M = 2A > 0$ such that

$$|f'(z)| \leq \frac{M}{|z|^{2-k_n}}$$
(1.7)

Using equation (1.7) and

$$\lim_{z \rightarrow \infty} F(z) = \lim_{z \rightarrow \infty} \int_{z_0}^z f'(s) ds$$

$$\leq \lim_{z \rightarrow \infty} \left| \int_{z_0}^z f'(s) ds \right|$$

$$\leq \lim_{z \rightarrow \infty} \int_{z_0}^z |f'(s)| ds$$

$$\leq \lim_{z \rightarrow \infty} \int_{z_0}^z \frac{M}{|z|^{2-k_n}} ds$$

$$= M \lim_{z \rightarrow \infty} \int_{z_0}^z \frac{1}{|z|^{2-k_n}} ds,$$
(1.8)

since $2 - k_n > 1$, then $\int_{z_0}^z \frac{1}{|z|^{2-k_n}} ds \rightarrow 0$, that means the limit of the integral (1.7) exists as z tend to infinity .

So there exists a number w_n such that $f(\infty) =: \lim_{z \rightarrow \infty} F(z) = w_n, \text{Im } z \geq 0$. Next we will prove the equation

(1.3). After taking the argument to the equation (1.5) we have

$$\arg f'(z) = \arg A - k_1 \arg(z - x_1) - k_2 \arg(z - x_2) - \dots - k_{n-1} \arg(z - x_{n-1})$$

then by using identity (1.1),(1.2) yields

$$\arg f'(z) = \arg A + \arg(z - x_1)^{-k_1} (z - x_2)^{-k_2} \cdots \arg(z - x_{n-1})^{-k_{n-1}}$$

$$\arg f'(z) = \arg A (z - x_1)^{-k_1} (z - x_2)^{-k_2} \cdots (z - x_{n-1})^{-k_{n-1}}$$

$$f'(z) = A (z - x_1)^{-k_1} (z - x_2)^{-k_2} \cdots (z - x_{n-1})^{-k_{n-1}}$$

Let $-k_1 = \frac{-\alpha_1}{x}$ then we have

$$f'(z) = A (z - x_1)^{\frac{-\alpha_1}{x}} (z - x_2)^{\frac{-\alpha_2}{x}} \cdots (z - x_{n-1})^{\frac{-\alpha_{n-1}}{x}}, \text{ and}$$

$$\int f'(z) = \int A (z - x_1)^{\frac{-\alpha_1}{x}} (z - x_2)^{\frac{-\alpha_2}{x}} \cdots (z - x_{n-1})^{\frac{-\alpha_{n-1}}{x}}$$

$$f(z) + c = \int A (z - x_1)^{\frac{-\alpha_1}{x}} (z - x_2)^{\frac{-\alpha_2}{x}} \cdots (z - x_{n-1})^{\frac{-\alpha_{n-1}}{x}}$$

$$f(z) = \int A (z - x_1)^{\frac{-\alpha_1}{x}} (z - x_2)^{\frac{-\alpha_2}{x}} \cdots (z - x_{n-1})^{\frac{-\alpha_{n-1}}{x}} - c$$

If $-c = B$ then

$$f(z) = B + \int A (z - x_1)^{\frac{-\alpha_1}{x}} (z - x_2)^{\frac{-\alpha_2}{x}} \cdots (z - x_{n-1})^{\frac{-\alpha_{n-1}}{x}} dz$$

$$= B + \int A (z - x_1)^{\frac{-\alpha_1}{x}} (z - x_2)^{\frac{-\alpha_2}{x}} \dots (z - x_{n-1})^{\frac{-\alpha_{n-1}}{x}} dz.$$

Next, since the argument of a product of the complex numbers are equal to the number of arguments of each factor, from equation (1.5) we have

$$\operatorname{arg} f'(z) = \operatorname{arg} A - k_1 \operatorname{arg}(z - x_1) - k_2 \operatorname{arg}(z - x_2) - \dots - k_{n-1} \operatorname{arg}(z - x_{n-1}). \tag{1.9}$$

The real numbers $x_1, x_2, \dots, x_{n-1}, x_n$ take on the real axis z -plane. If z is a real number, then the number

$$N_j = z - x_j, \tag{1.10}$$

is positive if z is greater than x_j and negative if z is less than x_j and

$$\operatorname{arg}(z - x_j) = \begin{cases} 0, & \text{if } z > x_j \\ \pi, & \text{if } z < x_j. \end{cases} \tag{1.11}$$

If $z = x$ and $x < x_j, j = 1, 2, 3, \dots, n - 1$ then

$$\operatorname{arg}(z - x_1) = \operatorname{arg}(z - x_2) = \dots = \operatorname{arg}(z - x_{n-1}) = \pi. \tag{1.12}$$

If $z = x$ and $x_{r-1} < x < x_r, j = 1, 2, \dots, r - 1, r, r + 1, \dots, n - 1$ and let

$$\phi_{r-1} = \operatorname{arg} f'(z) \tag{1.13}$$

then according to equation (1.9) and (1.11) and (1.13)

$$\begin{aligned} \operatorname{arg} f'(z) &= \operatorname{arg} A - k_1 \operatorname{arg}(z - x_1) - k_2 \operatorname{arg}(z - x_2) - \dots - k_{n-1} \operatorname{arg}(z - x_{n-1}) \\ \phi_{r-1} &= \operatorname{arg} A - k_r \operatorname{arg}(z - x_r) - k_{r+1} \operatorname{arg}(z - x_{r+1}) - \dots - k_{n-1} \operatorname{arg}(z - x_{n-1}) \\ &= \operatorname{arg} A - k_r \pi - k_{r+1} \pi - k_{r+2} \pi - \dots - k_{n-1} \pi \\ &= \operatorname{arg} A - (k_r - k_{r+1} - k_{r+2} - \dots - k_{n-1}) \pi \end{aligned} \tag{1.14}$$

and

$$\begin{aligned} \phi_r &= \operatorname{arg} A - k_{r+1} \operatorname{arg}(z - x_{r+1}) - k_{r+2} \operatorname{arg}(z - x_{r+2}) - \dots - k_{n-1} \operatorname{arg}(z - x_{n-1}) \\ &= \operatorname{arg} A - k_{r+1} \pi - k_{r+2} \pi - k_{r+3} \pi - \dots - k_{n-1} \pi \\ &= \operatorname{arg} A - (k_{r+1} - k_{r+2} - k_{r+3} - \dots - k_{n-1}) \pi \end{aligned} \tag{1.15}$$

Then

$$\phi_r - \phi_{r-1} = \frac{[\operatorname{arg} A - (k_{r+1} - k_{r+2} - k_{r+3} - \dots - k_{n-1}) \pi]}{[\operatorname{arg} A - (k_r - k_{r+1} - k_{r+2} - \dots - k_{n-1}) \pi]} \tag{1.16}$$

$$\phi_r - \phi_{r-1} = k_r \pi, \text{ with } j = 1, 2, 3, \dots, r - 1, r, \dots, n - 1.$$

Such that, if $z = x$ then $x_{j-1} < x < x_j, j = 1, 2, \dots, n - 1$ in the real axis z -plane from the left point x_j to his right, then the vector τ in w -plane change with angle $k_j \pi$, on the point of the image x_j , as shown in Figure 1.2. angle $k_j \pi$ is outside the terms of the z -plane at the point W_j .

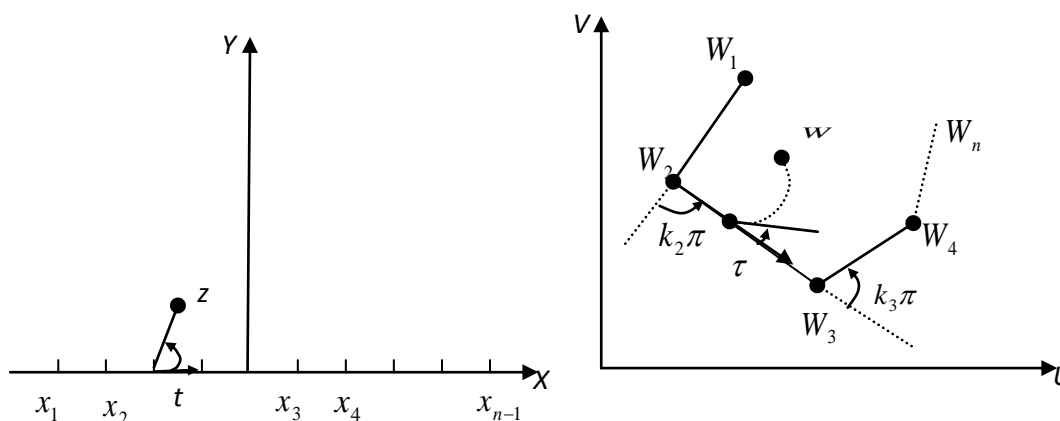


Figure 1.2. Mapping $f(z)$ with $z = x$ and $x_{j-1} < x < x_j$ (see [3])

It is assumed that the sides of the z -plane do not intersect each other and take opposite corners clockwise. Outside corners can be approximated by the angle between π and $-\pi$, so that $-1 < k_j < 1$. If the terms of n -closed, the number of outer corner is 2π . To prove it is seen to have sided closed $(n + 1)$, see Figure 1.3

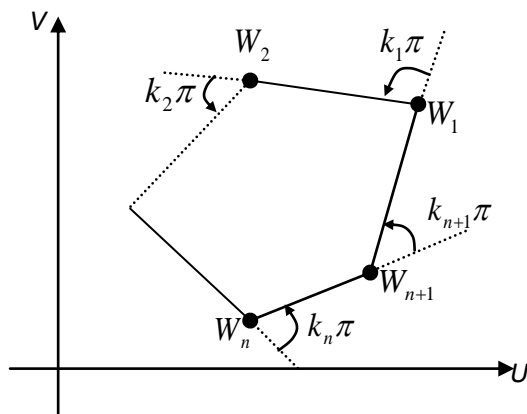


Figure 1.3. Closed n -image has $(n + 1)$ plane (see [3]).

It has known that $k_j\pi$ is the magnitude of the outer corner at the point W_j which is the image of a point x_j . If many terms have side $n + 1$, then

$$\begin{aligned} k_2\pi &= \phi_2 - \phi_1 \\ k_3\pi &= \phi_3 - \phi_2 \\ k_4\pi &= \phi_4 - \phi_3 \\ &\vdots \\ k_n\pi &= \phi_n - \phi_{n-1} \end{aligned}$$

While the angle $k_1\pi = \phi_1 - \phi_{n+1}$ and $k_{n+1}\pi = \phi_{n+1} + 2\pi - \phi_n$.

In terms of $-n$. $k_{n+1}\pi = 0$ so that $\phi_n = \phi_{n+1} + 2\pi$. Thus, the

$$\begin{aligned} k_1\pi + k_2\pi + k_3\pi + \dots + k_n\pi &= (\phi_1 - \phi_{n+1}) + (\phi_2 - \phi_1) + (\phi_3 - \phi_2) + \dots + (\phi_n - \phi_{n+1}) \\ (k_1 + k_2 + k_3 + \dots + k_n)\pi &= (\phi_n - \phi_{n+1}) \\ &= 2\pi \end{aligned}$$

$$k_1 + k_2 + k_3 + \dots + k_n = 2 \tag{1.17}$$

So it is clear that k_j with $j = 1, 2, 3, \dots, n$ satisfy the condition

$$k_1 + k_2 + k_3 + \dots + k_n = 2, -1 < k_j < 1.$$

End of proof.

V. ACKNOWLEDGEMENTS

I would like to thank Prof. Dr. Marjono and Dr. Bagus, for the encouragements.

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